



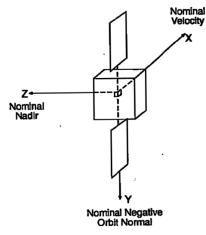
# **Orbital Mechanics**

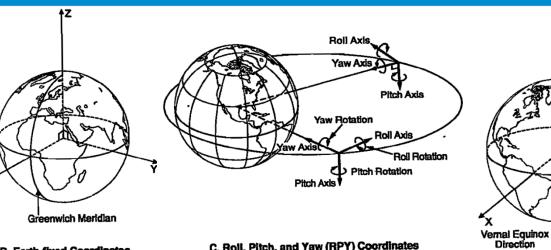
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#### Coordinate systems for spacecraft





A. Spacecraft-fixed Coordinates

**B. Earth-fixed Coordinates** 

C. Roll, Pitch, and Yaw (RPY) Coordinates

Coordinate Name	Fixed with Respect to	Center	Z-axis or Pole	X-axis or Ref. Point	Applications
Celestiai (inertiai)	Inertial space*	Earth <sup>†</sup> or spacecraft	Celestial pole	Vernal equinox	Orbit analysis, astronomy, inertial motion
Earth-fixed	Earth	Earth	Earth pole = celestial pole	Greenwich meridian	Geolocation, apparent satellite motion
Spacecraft- fixed	Spacecraft	Defined by engineering drawings	Spacecraft axistoward nadir	Spacecraft axis in direction of velocity vector	Position and orientation of spacecraft instruments
Local Horizontal <sup>‡</sup>	Orbit	Spacecraft	Nadir	Perpendicular to nadir toward velocity vector	Earth observations, attitude maneuvers
Ecliptic	Inertial space	Sun	Ecliptic pole	Vernal equinox	Solar system orbits, lunar/solar ephemerides

Some recommendations on choosing of a coordinate system:

• Earth-centered inertial for orbit problems

• Spacecraft-centered local horizontal for the Earth remote sensing missions

• Spacecraft-centered inertial for remote sensing missions of any other objects



Actually rotating slowly with respect to inertial space.

Earth-centered inertial coordinates are frequently called GCI (Geocentric Inertial).

Also called LVLH (Local Vertical/Local Horizontal), RPY (Roll, Pitch, Yaw), or Local Tangent Coordinates. ±

**D.** Celestial Coordinates

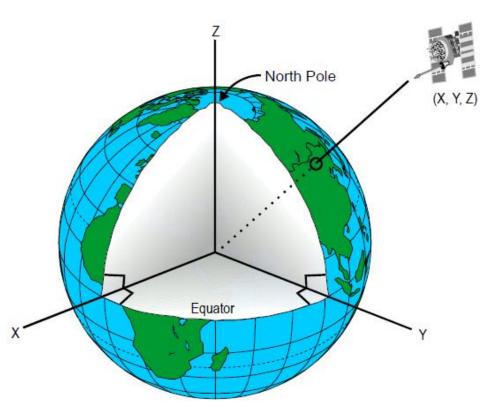


Axis directions:

the X axis is directed to the point of the vernal equinox;

the Z axis is directed along the direction of the angular velocity vector of the Earth's rotation (to the north);

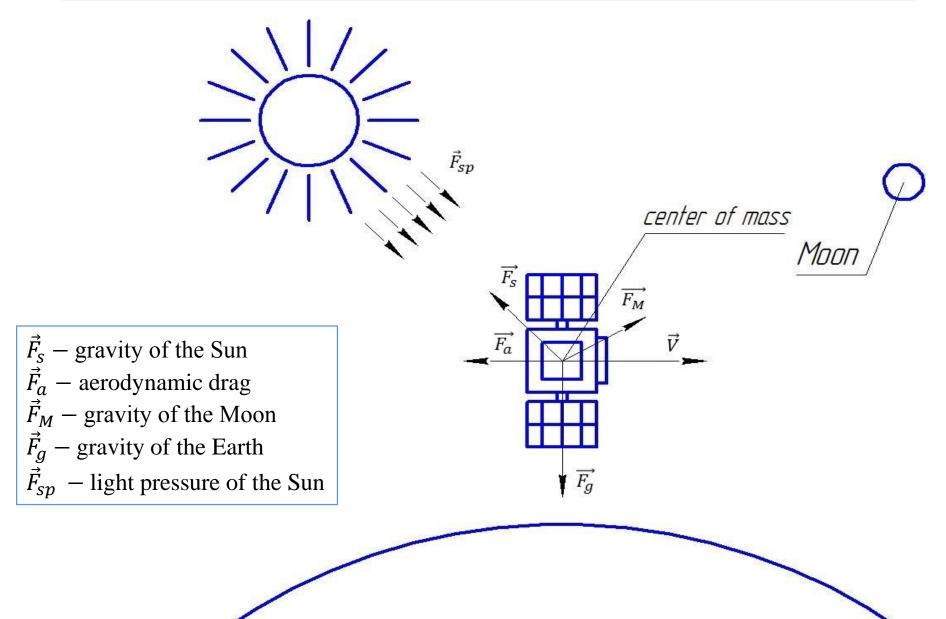
the Y axis completes the axis system to the right-handed coordinate system.





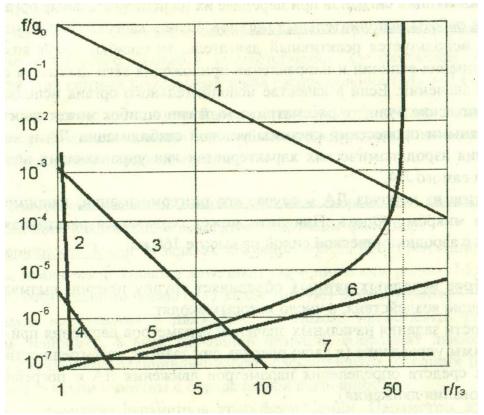


# What forces act on the a spacecraft in flight





#### Forces and accelerations that act on the spacecraft in flight



*f*-perturbing acceleration

- $g_0$  -acceleration of central gravity field (zero spherical harmonics)
- $r_{\!\scriptscriptstyle \Im}$  -Earth's radius
- r-radius vector of a spacecraft

1- *g* 

2

3

4

1

5

6

7

- 2- perturbation for aerodynamic drag
- 3- the second harmonic of the gravitational field of the Earth
- 4- fourth harmonic of the gravitational field of the Earth
- 5- force of gravity of the Moon
- 6- force of gravity of the Sun

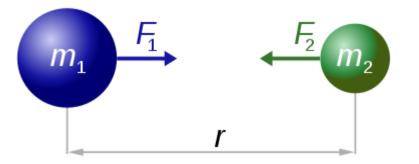
**GEO** 

7-force of light pressure of the Sun

LEO is an orbit around Earth with an altitude between 160 kilometers and 2000 kilometers







1. The equation for the magnitude of the force caused by gravity

$$\vec{F} = -\frac{\mu m}{r^2} \vec{r}_0 = -\frac{\mu m}{r^3} \vec{r}$$

 $\mu=GM - gravitational parameter$   $\vec{r}_o = \frac{\vec{r}}{r} - unit vector$  r - distance between thecenter of mass of the Earthand the center of mass of the spacecraft $<math display="block">\vec{r} - radius-vector of the spacecraft$ m - mass of a spacecraft Newton's law of universal gravitation

$$F_1 = F_2 = G \frac{m_1 m_2}{r^2}$$

2.Combining Newton's second law with universal gravitation law, we obtain an equation for the acceleration vector of a satellite:

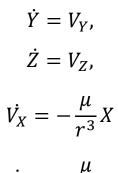
$$\vec{F} = m\vec{a} = -\frac{\mu m}{r^3}\vec{r}$$

$$\vec{\ddot{r}} + \frac{\mu}{r^3}\vec{r} = 0 \qquad (1)$$



Motion equation in inertial coordinate system

$$\vec{\ddot{r}} + \frac{\mu}{r^3}\vec{r} = 0$$



 $\dot{X} = V_X$ ,

$$\dot{V_Y} = -\frac{\mu}{r^3}Y$$

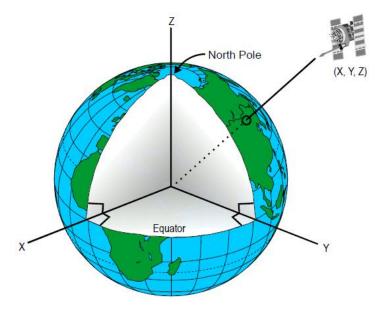
$$\dot{V_Z} = -\frac{\mu}{r^3}Z$$

 $\mu$  = 398602 km<sup>3</sup>/s<sup>2</sup>

Assumptions:

- 1) Central gravity field
  - 2) No other forces

3) Mass of a Satellite << Mass of the Earth







#### Equation of the orbit in the polar coordinate system

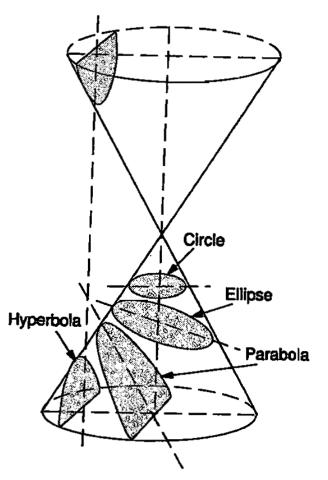
$$r = \frac{p}{1 + ecos(v)}$$
(5)

# Kepler's laws No1 of spacecraft motion

Motion of a spacecraft in the central gravitational field is made along a conical section. One of the focuses is located in the attracting center (the Earth), and the main focal axis coincides with the direction of the Laplace vector.

There is the following classification of orbits depending on the magnitude eccentricity:

e=0 – orbit is a circle 0 < e < 1 – orbit is a ellipse e=1 – orbit is a parabola e>1 – orbit is a hyperbola







Elliptic orbits are the most common in nature

The equation of the elliptical orbit is

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$
$$0 < e < l \qquad r = \frac{p}{1 + e \cos \nu}$$

a) If *e*,*p* are given then

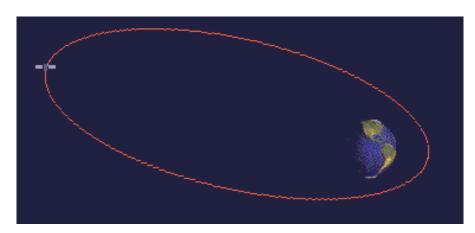
$$r_{\pi} = \frac{p}{1+e}, r_{\alpha} = \frac{p}{1-e},$$

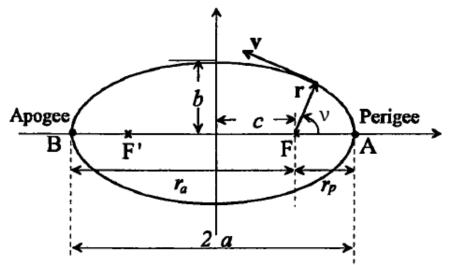
$$a = \frac{r_{\alpha} + r_{\pi}}{2} = \frac{p}{1-e^{2}},$$

$$c = \frac{r_{\alpha} - r_{\pi}}{2} = ae,$$

$$b = \sqrt{a^{2} - c^{2}} = a\sqrt{1-e^{2}} = \frac{p}{\sqrt{1-e^{2}}},$$

$$e = \frac{c}{a}.$$



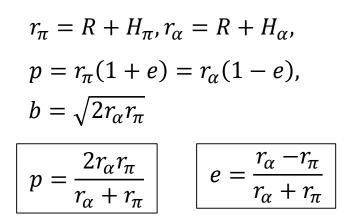




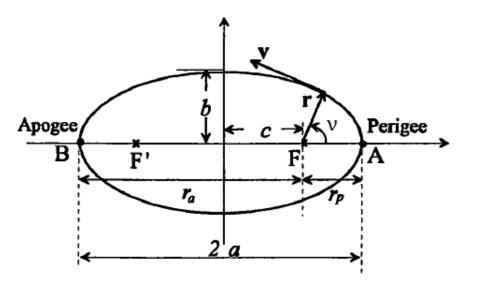
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b) If  $r_{\pi}$ ,  $r_{\alpha}$  are given then



$$V_{el} = \sqrt{\frac{\mu}{r} \left(2 - \frac{r}{a}\right)}$$







#### Kepler's equation

The time of motion along an elliptical orbit describes the Kepler's equation

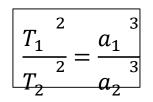
$$t - \tau = \frac{a^{3/2}}{\sqrt{\mu}} (E - \operatorname{esin} E)$$

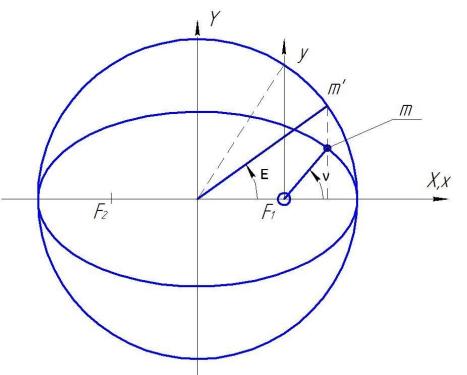
 $\tau$  - time of passage of pericentre E - eccentric anomaly



$$T = \frac{2\pi a^{3/2}}{\sqrt{\mu}}$$

Kepler's laws No3 of planetary motion





To predict the motion, the Kepler's equation is represented in the form of the transcendental equation:

$$E - e \sin E = M$$

$$M = \sqrt{\frac{\mu}{a^3}(t-\tau)}$$

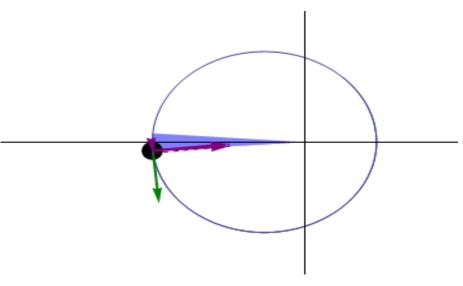




## Kepler's laws №2 of spacecraft motion

$$\vec{r} \times \vec{V} = \vec{C}$$

A line segment joining a spacecraft and the Earth sweeps out equal areas during equal intervals of time



The same (blue) area is swept out in a fixed time period. The green arrow is velocity. The purple arrow directed to the Earth is the acceleration. The other two purple arrows are components of acceleration. They are parallel and perpendicular to the velocity.







Velocity in circular orbit  $V_1 = \sqrt{\frac{\mu}{r}}$ 

The Escape velocity  $V_{\rm e} = \sqrt{\frac{2\mu}{r}} = \sqrt{2}V_1$  – is the minimum speed needed for a free, non-propelled object to escape from the gravitational influence of a massive body

	1 <sup>st</sup> , km/s	2 <sup>nd</sup> , km/s
Earth	7,91	11,2
Moon	1,68	2,38
Mars	3,55	5



# Elements of the orbit in space

The main **two elements that define the shape and size** of the ellipse:

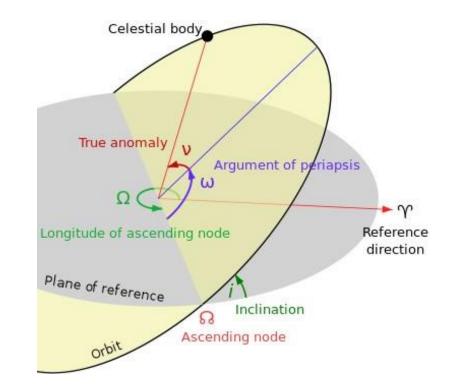
**Eccentricity (e)**—shape of the ellipse, describing how much it is elongated compared to a circle (not marked in diagram).

**Semimajor axis (a)** —the sum of the periapsis and apoapsis distances divided by two.

**Two elements define the orientation** of the orbital plane in which the ellipse is embedded:

**Inclination (i)**—vertical tilt of the ellipse with respect to the reference plane, measured at the ascending node (where the orbit passes upward through the reference plane, the green angle i in the diagram).

**Longitude of the ascending node** ( $\Omega$  or  $\Omega$ )—horizontally orients the ascending node of the ellipse (where the orbit passes upward through the reference plane) with respect to the reference frame's vernal point (the green angle  $\Omega$  in the diagram).

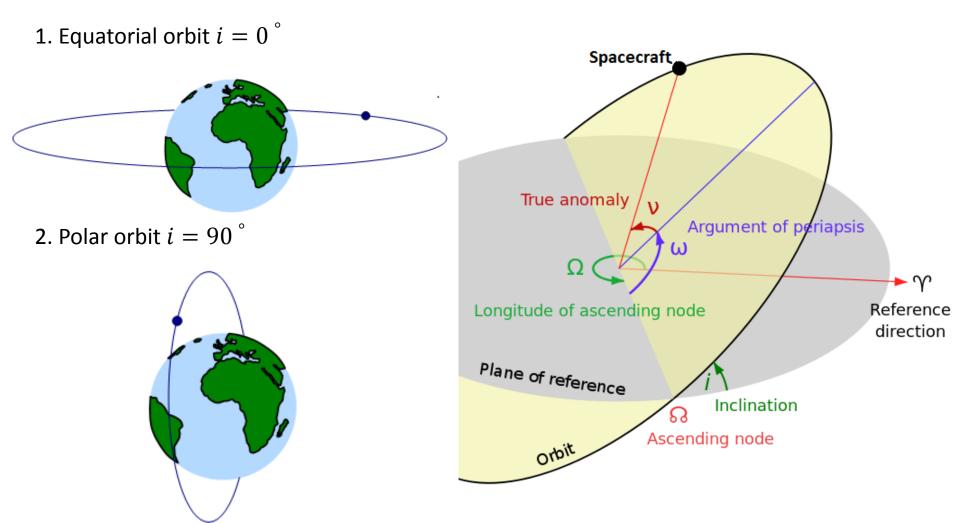


<u>Argument of periapsis ( $\omega$ )</u> defines the orientation of the ellipse in the orbital plane, as an angle measured from the ascending node to the periapsis (the closest point the satellite object comes to the primary object around which it orbits, the blue angle  $\omega$  in the diagram).

<u>**True anomaly**</u> (v,  $\theta$ , or f) at epoch (M0) defines the position of the orbiting body along the ellipse at a specific time (the "epoch").



Inclination belongs to the range  $0^{\circ} < i < 90^{\circ}$ 

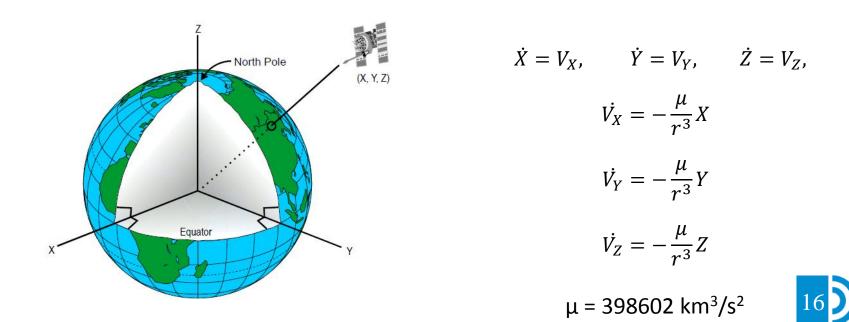






 $X = r(\cos u \cos \Omega - \sin u \cos i \sin \Omega),$   $Y = r(\cos u \sin \Omega + \sin u \cos i \cos \Omega),$  $Z = r \sin u \sin i.$ 

 $V_x = V_r(\cos u \cos \Omega - \sin u \cos i \sin \Omega) - V_n(\cos \Omega \sin u + \sin \Omega \cos u \cos i),$   $V_y = V_r(\cos u \sin \Omega + \sin u \cos i \cos \Omega) - V_n(\sin \Omega \sin u - \cos \Omega \cos u \cos i),$  $V_z = V_r \sin u \sin i + V_n \cos u \sin i,$ 





# **THANK YOU**

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